

# Installation and Maintenance

## Tool changers TC100–TC1000

M0416-1

Tool changers | Swivels | Swivels Tool changers | Grippers | Hose packages | Valve Units | Tool systems





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# 1 INTRODUCTION

**Robot System Products** is a front-rank provider of peripheral products for high performance robot applications. We provide complete tool systems solutions for your robot installations, aiming to improve your productivity with the most reliable and cost-effective tooling on the market. Continuously we explore emerging technologies, working with leading edge design.

**Robot System Products** has a wide range of standard robot peripheral products:



- Tool changers
- Swivels
- Swivel tool changers
- CiRo
- Grippers
- Hose Packages
- Valve units
- Tool systems
- Tool parking systems

**Robot System Products'** tool changers are constructed to maximize the flexibility and reliability of your robot fleet. Through our patented locking device TrueConnect™ robustness and high safety are combined with low weight and compactness. With our swivels compressed air, water, electrical and data signals as well as weld and servo power are transferred to your tools with robot motion capabilities fully maintained. Our swivel tool changers unite the TrueConnect™ mechanism with our swivel technology, combining the best out of the two technologies. With RSP's cost-effective CiRo, cables and hoses can be freely selected with high robot flexibility maintained, and space requirements reduced. Our integrated tool systems are delivered as complete plug-and-play solutions designed for quick and simple installation.

**Robot System Products'** product lines are available for all major robot brands and come with complete documentation. 3D-models for simulation are available for download at: [robotsystemproducts.com](http://robotsystemproducts.com).

## 1.1 Installation and Maintenance manual

This document describes how the tool changers, TC100, TC250, TC350, TC500 and TC1000, including corresponding tool attachments and options for transfer of signals and air, are installed and replaced. In addition, the document describes required maintenance activities, including inspection, cleaning, lubrication, replacement of wear parts, required tools and products and disposal and recycling.

The *Product Descriptions* of each respective unit are available as separate documents containing product information, drawings, technical data, electrical and pneumatic diagrams and lists of spare parts.

## 1.2 Safety

### 1.2.1 General

The integrator installing the tool changer into the system must follow the safety demands stated in standards and provisions applicable in the country where the tool changer system is to be installed. The products are all prepared for CE-certification.

The user of the Robot System Products' tool changer is responsible that law and directives applicable in respective countries, with regards to safety, are followed. The user is also responsible to guarantee that all safety devices are installed correctly.



**WARNING!**

Never carry out service work on a robot that has not been taken out of operation. See safety information for the robot.



**WARNING!**

Only perform work on tools attached to the tool changer if the air pressure is safely switched off.



**WARNING!**

Be aware that tool changer and tool attachment may cause personal injury and equipment damage if dropped.



**NOTE!**

The tool changer shall always be in locked position, also when empty, to avoid unexpected locking if air pressure is lost.



**WARNING!**

Electric signals must be disconnected/switched off when docking the tool attachment. This is to prevent sparking between signal pins and tool attachment.

### 1.2.2 Explanation of warnings

The warnings in this document are specific to the products in this manual. It is expected that the user also pay attention to certain notifications from the robot manufacturer and/or the manufacturers of other components used in the installation.



**WARNING!**

The warning sign will make you aware that a situation could result in potential serious injury or damage to equipment.



**NOTE!**

The note sign will alert you about something important to consider.

## 1.3 Tightening torques

### Tightening torques for mounting (screw class 8.8)

Dimension	Torque
M8	24 Nm
M10	47 Nm
M12	82 Nm
M14	131 Nm
M16	200 Nm

### Tightening torques for mounting (screw class 12.9)

Dimension	Torque
M8	41 Nm
M10	79 Nm
M12	138 Nm
M14	221 Nm
M16	338 Nm

## 1.4 Recommended equipment

### Equipment recommended for installation and maintenance work

Tools	Applications
Complete set of Allen keys	For all socket head cap screws
Torque wrench	For dismounting and mounting
Torx keys	For dismounting and mounting
Pair of pliers	For dismounting the signal pins
Screwdriver	For removing the air sealings

## 1.5 Required products

Product	Specification	Note
Grease I1934	Renolit HLT2	For air sealings and locking balls.
Cleaning agent	Industrial alcohol or similar	For cleaning of tool changer and tool attachment.
Glue	Loctite 480 (or similar)	For gluing the air sealings.
Cloth	Lint free cloth	For cleaning.

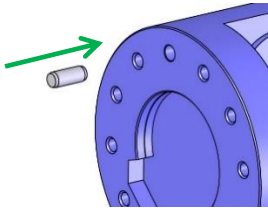
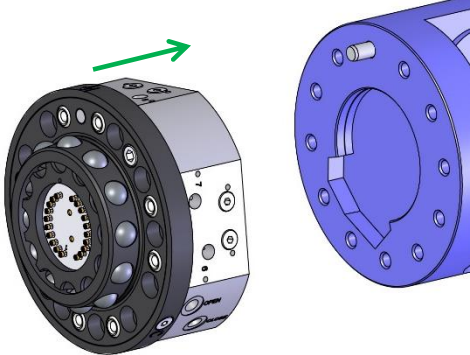
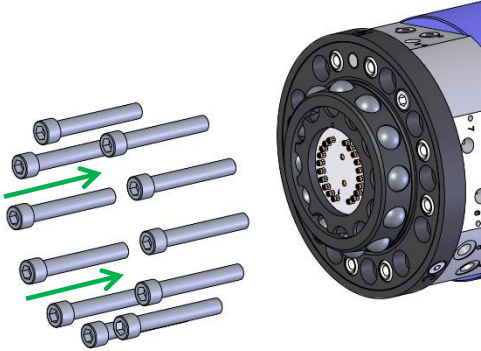


**NOTE!** Chemical resistance protective gloves are recommended when using grease or cleaning agents such as industrial alcohol. Safety goggles are recommended when working with cleaning agents such as industrial alcohol. Adequate ventilation should be provided when chemical substances are used.

## 2 INSTALLATION

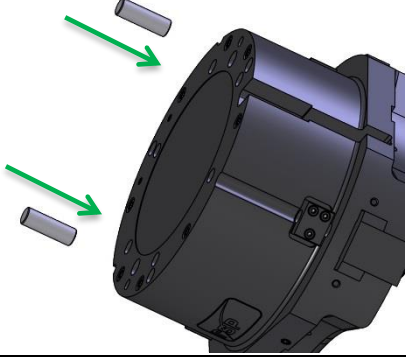
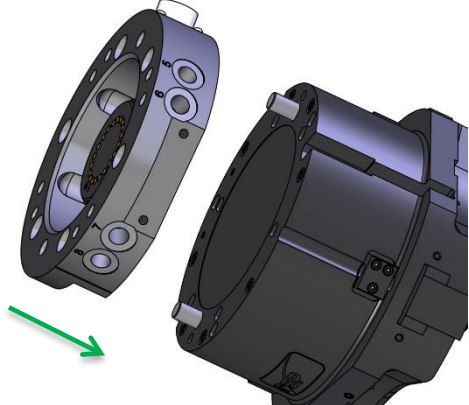
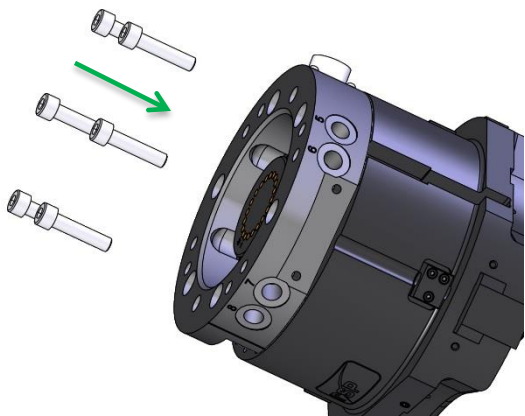
### 2.1 Installation of tool changer on robot



	Action	Note
1	<b>Safety</b>	Read the safety <a href="#">section 1.2</a> .
2	<b>Service position</b>	Place the robot in service position.
3	<b>Power off</b>	Switch the power off and lock the circuit breaker. <b>NOTE!</b> Read the safety chapter for the robot.
4	<b>Mount guide pin</b> 	Press the enclosed guide pin into the robot flange. <i>Alternatively, if adaptation plate is used:</i> Mount the adaptation plate on the robot flange (see tightening torques above). Press the enclosed guide pin into the adaptation plate.
5	<b>Fit tool changer</b> 	Lift the tool changer to the robot flange (or adaptation plate). The arrow on the front of the tool changer indicates the position of the hole for the guide pin. Make sure that the guide pin is fitted to the guide hole in the tool changer.  <b>WARNING!</b> The tool changer may cause personal injury and equipment damage if dropped.
6	<b>Mount tool changer</b> 	Mount the tool changer with the enclosed screws. Use an Allen key for tightening (see tightening torques above).
7	<b>Connect air hoses</b>	Connect the air hoses according to markings. Pneumatic diagrams are found in the <i>Product Description</i> of respective unit.
8	<b>Connect electrical signals</b> (electrical versions only)	Connect electrical connectors in accordance with selected unit. Circuit diagrams are found in the <i>Product Description</i> of respective unit.
9	<b>Power on</b>	Unlock the circuit breaker and switch the power on.



## 2.2 Installation of tool attachment on tool

	Action	Note
1	<b>Safety</b>	Read the safety <a href="#">section 1.2</a> .
2	<b>Mount guide pins</b> 	Press the two guide pins into the corresponding holes on the tool.
3	<b>Fit tool attachment</b> 	Lift and fit the tool attachment, using the guide pins, into its appropriate guide holes.  <b>WARNING!</b> The tool attachment is heavy and may cause personal injury and equipment damage if dropped.
4	<b>Mount tool attachment</b> 	Fastening screws can be entered either from the tool attachment side or the tool side. Screws are specified in the <i>Product Description</i> of respective tool attachment. Mount the tool attachment using a torque wrench. See tightening torques above.  <b>NOTE!</b> For TA100 fastening screws can only be entered from the tool attachment side.
5	<b>Connect air hoses</b>	Connect air hoses to the tool attachment. Pneumatic diagrams are found in the <i>Product Description</i> of respective unit.
6	<b>Connect signals (electrical versions only)</b>	Connect electrical connectors in accordance with selected unit. Circuit diagrams are found in the <i>Product Description</i> of respective unit.



## 2.3 Programming

The following will ensure a correct docking position.

	Action
1	Attach a spare tool attachment to the tool changer.
2	Position the spare tool attachment above the tool attachment that is mounted at the tool.
3	The correct position is found when the tool attachments are parallel, centered and the engraved arrows are on the same line.
4	Save the position. The robot can move to this position with high speed.
5	Dismount the spare tool attachment.
6	Go back to the saved position and move the tool changer (in axis 6 direction) the remaining distance to the tool attachment (mounted at the tool).
7	Save the position. The robot should move the final distance to this position with low speed.

## 3 MAINTENANCE AND SERVICE

The tool changers and the tool attachments must be maintained regularly to ensure proper function. The specified intervals are approximate and valid under normal conditions, corresponding to 2 tool changes per minute during 2 work shifts per working day, i.e. 42.000 tool changes per month. Under extreme conditions, such as dirty environments or extreme robot movements, the intervals should be shortened. Consider the table as a guide and update as your production experience of each system increases.



### NOTE

Read the safety [section 1.2](#) before any maintenance activities are carried out.



### NOTE!

Tool changers must only be dismantled and repaired by Robot System Products during the warranty period. Otherwise the warranty will not be valid.

### 3.1 Maintenance scheme

#### 3.1.1 Every second week

The following maintenance activities should be carried out every second week.

Activity	Equipment		Description
Inspection	Tool changer	General	Visual inspection ( <a href="#">section 3.2.1</a> ).
		Locking balls	Check locking balls ( <a href="#">section 3.2.1</a> ).
		Air sealings	Check air sealings ( <a href="#">section 3.2.1</a> ).
		Spring-loaded pins	Check spring-loaded signal ( <a href="#">section 3.2.1</a> ).
	Tool attachment	General	Visual inspection of tool attachment and cables ( <a href="#">section 3.2.2</a> ).
Cleaning	Tool attachment	Signal contacts	Clean contact surfaces ( <a href="#">section 3.2.2</a> ).

#### 3.1.2 Every six-months or 250,000 tool changes

The following maintenance activities should be carried out every six-months or 250,000 tool changes, whichever comes first.

Activity	Equipment		Description
Cleaning and lubrication	Tool changer	Locking balls	Clean locking balls and add new lubrication ( <a href="#">section 3.2.3</a> ).
		Air sealings	Clean air sealings ( <a href="#">section 3.2.3</a> ).
		Spring-loaded pins	Clean spring-loaded signal pins ( <a href="#">section 3.2.3</a> ).
	Tool attachment	Locking cavities	Clean the cavities of the locking balls ( <a href="#">section 3.2.4</a> ).
		Contact surfaces	Clean the contact surfaces of air sealings ( <a href="#">section 3.2.4</a> ).

#### 3.1.3 To replace when damaged or worn-out


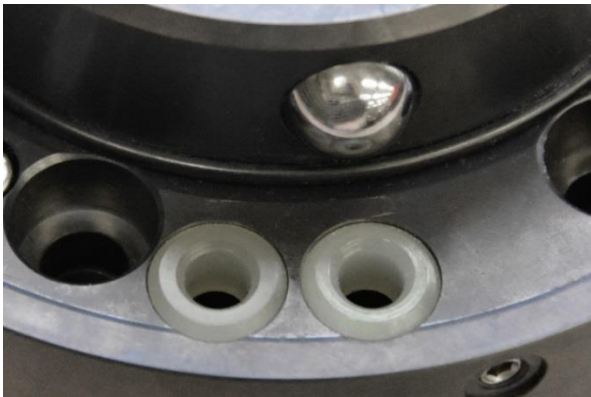
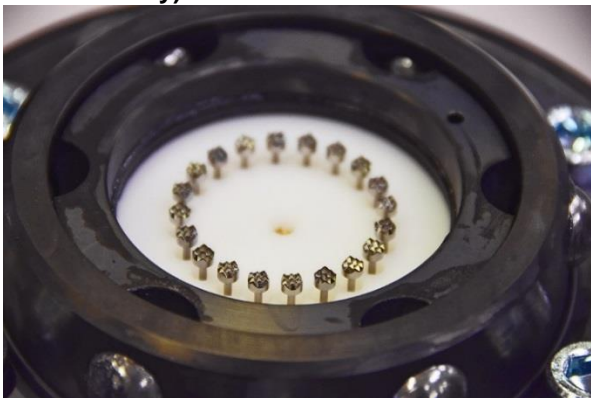
Equipment		Description
Swivel tool changer	Air sealings	See <a href="#">section 4.3.1</a> .
	O-ring around the ball holder	See <a href="#">section 4.3.2</a> .
	Spring-loaded signal pins (electrical versions only)	See <a href="#">section 4.3.3</a> .

## 3.2 Specification of maintenance activities

### 3.2.1 Visual inspection of tool changer


The following maintenance activities should be carried out on the TC every 2<sup>nd</sup> week.



Action	Note
<b>Check locking balls</b> 	<p>Check each ball to make sure it moves freely. For cleaning and lubrication of balls <a href="#">see section 3.2.3</a>.</p> <p><b>NOTE!</b> If balls get stuck there is a risk that the tool attachment jams.</p> <p><b>WARNING!</b> Risk of getting squeezed between piston and ball holder when the piston is taking closed position</p>
<b>Check air sealings</b> 	<p>Check that the air sealings are clean. For cleaning <a href="#">see section 3.2.3</a>.</p> <p>Check that the air sealings are not damaged. For making replacements see <a href="#">section 4.3.1</a>.</p>
<b>Check spring-loaded signal pins (electrical versions only)</b> 	<p>Check that the spring-loaded signal pins are clean. For cleaning <a href="#">see section 3.2.3</a>.</p> <p>Check that the spring-loaded signal pins are not worn-out or damaged. For making replacements see <a href="#">section 4.3.3</a>.</p>
<b>Check cables and hoses</b>	Check for damages and squeezing, replace if damaged.
<b>Check rotation stops</b>	Check that rotation stops are not worn-out or damaged, replace if damaged.
<b>Check tool changer in general</b>	Check tool changer for damages. For replacement see <a href="#">section 4.1</a> .

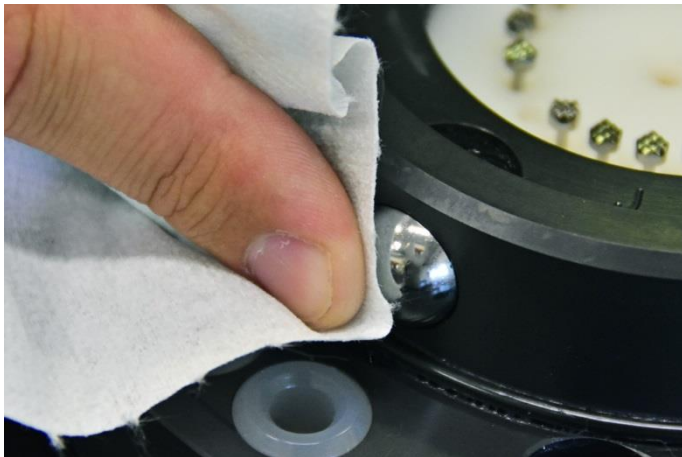
### 3.2.2 Visual inspection and cleaning of tool attachment

The following maintenance activities should be carried out on the TA every 2<sup>nd</sup> week.

Action	Note
<b>Clean contact surface (electrical versions only)</b> 	Wipe the contact surface with a lint free cloth.
<b>Check cables and hoses</b>	Check cables and hoses for damages and squeezing, replace if damaged.
<b>Check tool attachment in general</b>	Check the tool attachment for damages. For replacement see <a href="#">section 4.2</a> .

### 3.2.3 Cleaning and lubrication of tool changer

The following maintenance activities should be carried out on the TC every 6<sup>th</sup> month or after 250,000 tool changes, whichever comes first.

Action	Note
<b>Clean locking balls</b> 	Check the locking balls and wipe them clean with a lint free cloth.  <b>WARNING!</b> Risk of getting squeezed between piston and ball holder when the piston is taking closed position







#### Lubricate locking balls



Apply a small amount of grease (Renolit HLT2) on the locking balls.

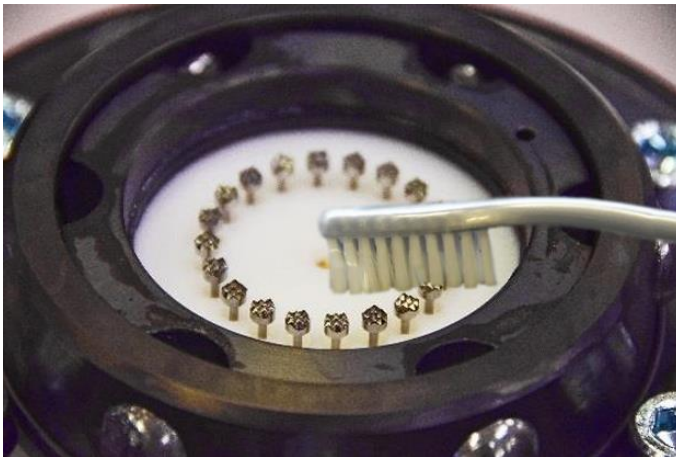
**NOTE!** It is important that this is done or else there is a risk that the tool attachment jams.

#### Clean air sealings



Wipe air sealings clean with a lint free cloth.

#### Clean spring-loaded signal pins (electrical versions only)



Clean the contact surfaces of the spring-loaded signal pins with a nylon brush.



**NOTE!**  
Signal pins shall be cleaned whenever blackened.



### 3.2.4 Cleaning and lubrication of tool attachment

The following maintenance activities should be carried out on the TA every 6th month or after 250,000 tool changes, whichever comes first.

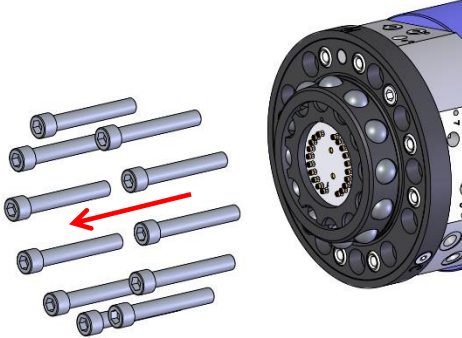
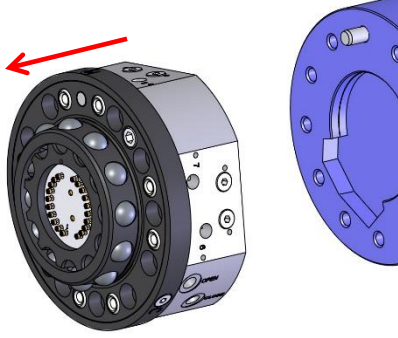


Action	Note
<b>Clean locking cavities</b>  A close-up photograph showing a person's thumb using a white lint-free cloth to wipe the inner surface of a locking cavity. The cavity is part of a white plastic component with a ring of small gold-colored pins around its perimeter. A dark grey metal component is visible in the background.	Clean the cavities of the locking balls with a lint free cloth.  <b>NOTE!</b> It is important that this is done or else there is a risk that the tool attachment jams.
<b>Clean contact surfaces of air sealings</b>  A close-up photograph showing a person's thumb using a white lint-free cloth to wipe the contact surface of an air sealing. The surface is a dark grey metal plate with several circular holes.	Wipe the contact surfaces of the air sealings clean with a lint free cloth.

## 4 DISMOUNTING AND REPLACEMENT

### 4.1 Replacement of tool changer

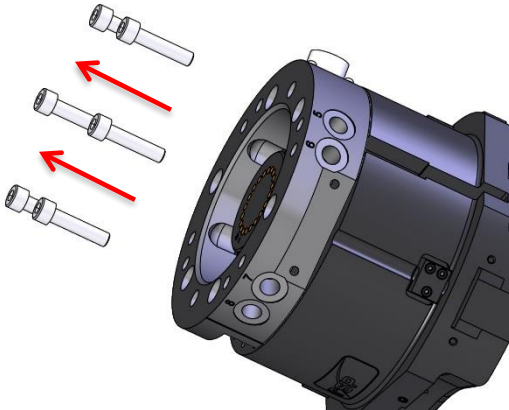
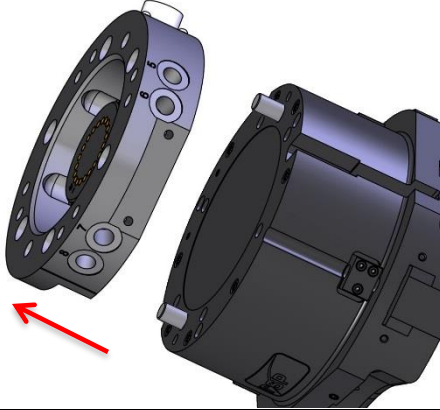


	Action	Note
1	<b>Safety</b>	Read the safety <a href="#">section 1.2</a> .
2	<b>Dismount tool</b>	Leave tool, with tool attachment mounted, in tool stand.
3	<b>Service position</b>	Place the robot in service position. <b>NOTE!</b> The tool change function shall be in locked position.
4	<b>Power off</b>	Switch the power off and lock the circuit breaker. <b>NOTE!</b> Read the safety chapter for the robot.
5	<b>Pneumatic air off</b>	<b>NOTE!</b> The pressure in the pneumatic system must be released before dismounting begins.
6	<b>Dismount hoses</b>	Dismount the air hoses from the tool changer. <b>NOTE!</b> Make sure that no dirt enters the air hoses.
7	<b>Release electrical connectors</b>	<b>NOTE!</b> Handle the contact with care, as it is sensitive to mechanical damage. Make sure no dirt enters contacts.
8	<b>Remove screws</b> 	Remove the screws holding the tool changer to the robot flange.  <b>WARNING!</b> The tool changer is heavy and may cause personal injury and equipment damage if dropped.  <b>NOTE!</b> Be careful not to damage the signal pins.
9	<b>Dismount tool changer</b> 	<b>NOTE!</b> A guide pin is mounted between the tool changer and the robot flange.
10	<b>Clean robot flange</b>	Clean the robot flange/adaptation plate using a lint free cloth.
11	<b>Mount replacement tool changer</b>	Follow instructions in <a href="#">section 2.1</a> .



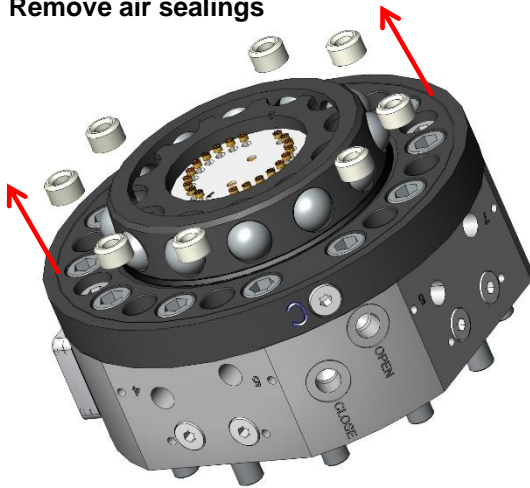
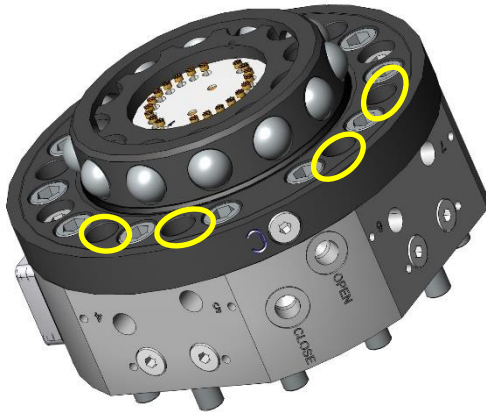
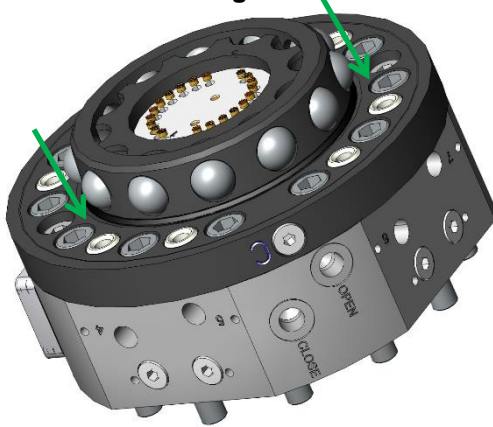
## 4.2 Replacement of tool attachment



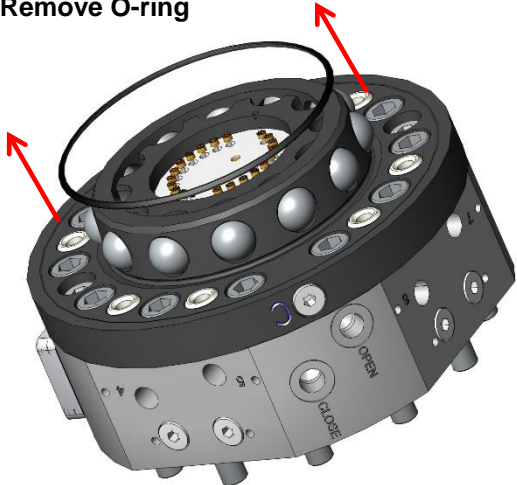
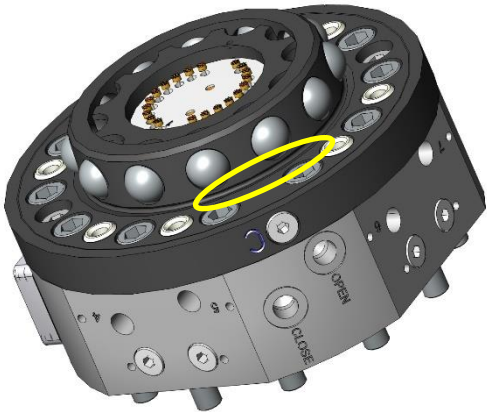
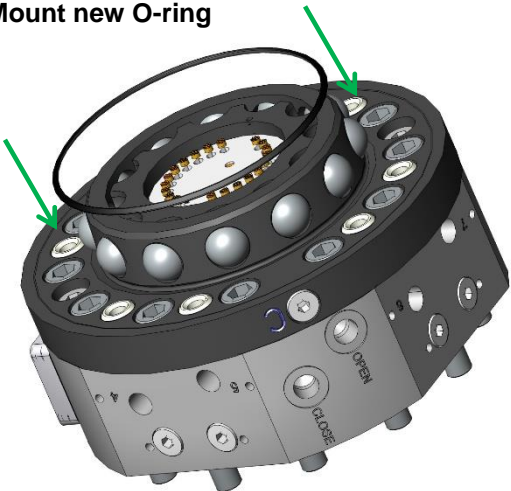
	Action	Note
1	<b>Safety</b>	Read the safety <a href="#">section 1.2</a> .
2	<b>Undock tool</b>	Undock tool attachment, with tool mounted, in a safe and fully supported position for dismantling.
3	<b>Release electrical connections</b>	<p>Disconnect electric power and signals.</p> <p><b>NOTE!</b> Handle contacts with care, as they are sensitive to mechanical damage. Make sure that no dirt enters the contacts.</p>
4	<b>Dismount hoses</b>	<p>Dismount the air hoses from the tool attachment.</p> <p><b>NOTE!</b> Make sure that no dirt enters the air hoses.</p>
5	<b>Remove screws</b> 	<p>Unscrew and remove the screws holding the tool attachment to the tool.</p> <p><b>WARNING!</b> The tool attachment is heavy and may cause personal injury and equipment damage if dropped.</p>
6	<b>Dismount tool attachment</b> 	<p><b>NOTE!</b> A guide pin is mounted between the tool attachment and the tool.</p>
7	<b>Clean the flange at the tool</b>	Clean flange at the tool using a lint free cloth.
8	<b>Mount tool attachment</b>	Follow instructions in <a href="#">section 2.2</a> .

## 4.3 Replacement of wear parts

### 4.3.1 Replacement of air sealing

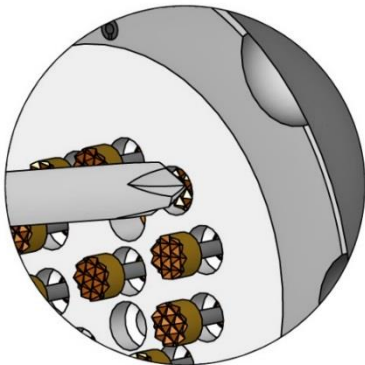
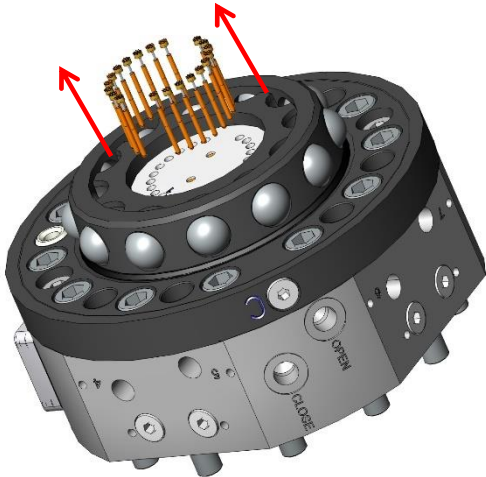
	Action	Note
1	<b>Remove air sealings</b> 	Remove the air sealings from the tool changer with a screwdriver.
2	<b>Clean sealing holes</b> 	Wipe clean the sealing holes. Remove all remaining parts of sealings and glue.
3	<b>Mount new air sealings</b> 	Glue the new air sealings in the sealing grooves. Use a small amount of Loctite 480 (or similar). Press the sealings 60-120 seconds until the glue hardens.

4.3.2 Replacement of O-ring

	Action	Note
1	<b>Remove O-ring</b> 	Remove the O-ring on the ball holder at the tool changer
2	<b>Clean surface</b> 	Clean the surface at the O-ring location.
3	<b>Add grease</b>	Add a small amount of grease (Renolit HLT2) on the new O-ring
4	<b>Mount new O-ring</b> 	

4.3.3 Replacement of signal pins (electric versions only)

	Action	Note
1	Power off	Switch the power off and lock the circuit breaker.
2	Remove signal pins	Pull out the signal pins from the tool changer with a pair of pliers.
3	Replace signal pins	Fit the new signal pins by pushing them into the sleeves.
4	Power on	Unlock the circuit breaker and switch the power on.



**NOTE!** The signal pins should be fully pressed into the sleeve using a small screwdriver.



## **5 DISPOSAL AND RECYCLING**

### **Taking care of spent equipment**

Used equipment must be taken care of in an environmentally-friendly way.

When disposed of, a major share of the material, or its energy content, can be recycled. The quantities possible to recycle vary depending on technical resources and practises in respective country. Non-recyclable components shall be handed over to an authorized environmental waste treatment facility for destruction or disposal.

### **Electronics**

Electronic equipment shall be sent to an authorized recycling company or sorted into different component materials and treated as such.

### **Metals**

Metals can, in general, be melted down, recycled and used in new products. They shall be sorted according to type and surface coating and handed over to an authorized recycling facility.

Metal components of steel and aluminium are substantial in size and easy to identify. Copper and brass are primarily used in transmission of electric power and in water/air modules. Brass may include small alloy of lead. Silver or gold plating of contact surfaces may occur.

### **Plastics**

Thermoplastics can, in general, be re-heated and recycled without any major loss of quality. They shall be handed over to an authorized recycling facility. POM occurs in swivel housings, etc. PTFE in some sealings.

### **Rubber**

Rubber shall be handed over to an authorized environmental waste treatment facility either for recycling, disposal or destruction. Rubber occurs in O-rings.

### **Other material**

All other material shall be sorted and handed to an authorized environmental waste treatment facility in accordance with national legislation.





